A New Model of Biomechanical Motion: A Revolution in Stroke Rehabilitation Maisie Keogh Department of Biomedical Engineering, Wolfson Centre, University of Strathclyde Glasgow, UK.

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Stroke is the third leading cause of death and disability combined globally. With the financial costs of rehabilitation increasing and currently one physiotherapist for every 1,136 people in the UK, new and innovative methods of stroke rehabilitation are needed.



A fusion of active tracking clusters and inertial measurement units provide a more complete **model** of **biomechanical motion** of the lower limbs. This method has been show effective when compared to the gold standard known as Plug-in-Gait. When used in a **rehabilitation gym environment** it



allows for **real-time visual feedback** of movement directly to the stroke survivor, thus reducing the reliance on physiotherapist.

Individual reflective markers are detected by cameras allowing for a **traditional model** of motion to be visualised, however this **requires a clinician** to interpret and feedback to the patient.

> A fusion of **clusters** and **IMUs** can be attached to segments of the **lower limbs** with motion tracked using alternative cameras. Data from these devices can be streamed through a custom-made **C++ program to Unreal Engine** providing **real-time** visualisation of movement.

Active tracking clusters called **Pulsars** provide **positional data** but are unable to determine how fast your limb is moving. Inertial measurement units (IMUs) provide **velocity data** but cannot tell where you are located in 3D space. By creating a **fusion** of the two technologies we can provide an **enhanced model of motion**.

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